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The book is written for an undergraduate course on the Feedback Control Systems. It provides comprehensive explanation of theory and practice of control system engineering. It elaborates various aspects of time domain and frequency domain analysis and design of control systems. Each chapter starts with the background of the topic. Then it gives the conceptual knowledge about the topic dividing it in various sections and subsections. Each chapter provides the detailed explanation of the topic, practical examples and variety of solved problems. The explanations are given using very simple and lucid language. All the chapters are arranged in a specific sequence which helps to build the understanding of the subject in a logical fashion. The book starts with explaining the various types of control systems. Then it explains how to obtain the mathematical models of various types of systems such as electrical, mechanical, thermal and liquid level systems. Then the book includes good coverage of the block diagram and signal flow graph methods of representing the various systems and the reduction methods to obtain simple system from the analysis point of view. The book further illustrates the steady state and transient analysis of control systems. The book covers the fundamental knowledge of controllers used in practice to optimize the performance of the systems. The book emphasizes the detailed analysis of second order systems as these systems are common in practice and higher order systems can be approximated as second order systems. The book teaches the concept of stability and time domain stability analysis using Routh-Hurwitz method and root locus method. It further explains the fundamentals of frequency domain analysis of the systems including co-relation between time domain and frequency domain. The book gives very simple techniques for stability analysis of the systems in the frequency domain, using Bode plot, Polar plot and Nyquist plot methods. It also explores the concepts of compensation and design of the control systems in time domain and frequency domain. The classical approach loses the importance of initial conditions in the systems. Thus, the book provides the detailed explanation of modern approach of analysis which is the state variable analysis of the systems including methods of finding the state transition matrix, solution of state equation and the concepts of controllability and observability. The variety of solved examples is the feature of this book which helps to inculcate the knowledge of the design and analysis of the control systems in the students. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting.

The book is written for an undergraduate course on the theory of Feedback Control Systems. It provides comprehensive explanation of theory and practice of control system engineering. It elaborates various aspects of time domain and frequency domain analysis and design of control systems. Each chapter starts with the background of the topic. Then it gives the conceptual knowledge about the topic dividing it in various sections and subsections. Each chapter provides the detailed explanation of the topic, practical examples and variety of solved problems. The explanations are given using very simple and lucid language. All the chapters are arranged in a specific sequence which helps to build the understanding of the subject in a logical fashion. The book starts with explaining the various types of control systems. Then it explains how to obtain the mathematical models of various types of systems such as electrical, mechanical, thermal and liquid level systems. Then the book includes good coverage of the block diagram and signal flow graph methods of representing the various systems and the reduction methods to obtain simple system from the analysis point of view. The book further illustrates the steady state and transient analysis of control systems. The book covers the fundamental knowledge of controllers used in practice to optimize the performance of the systems. The book emphasizes the detailed analysis of second order systems as these systems are common in practice and higher order systems can be approximated as second order systems. The book teaches the concept of stability and time domain stability analysis using Routh-Hurwitz method and root locus method. It further explains the fundamentals of frequency domain analysis of the systems including co-relation between time domain and frequency domain. The book gives very simple techniques for stability analysis of the systems in the frequency domain, using Bode plot, Polar plot and Nyquist plot methods. It also explores the concepts of compensation and design of the control systems in time domain and frequency domain. The classical approach loses the importance of initial conditions in the systems. Thus the book provides the detailed explanation of modern approach of analysis which is the state variable analysis of the systems including methods of finding the state transition matrix, solution of state equation and the concepts of controllability and observability. The book also introduces the concept of discrete time systems including digital and sample data systems, z-transform, difference equations, state space representation, pulse transfer functions and stability of linear discrete time systems. The variety of solved examples is the feature of this book which helps to inculcate the knowledge of the design and analysis of the control systems in the students. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting.

Focuses on the first control systems course of BTech, JNTU, this book helps the student prepare for further studies in modern control system design. It offers a profusion of examples on various aspects of study.

This monograph presents the state-of-the-art developments in the design of behaviorally and structurally optimal liveness-enforcing Petri net supervisors with computationally tractable approaches. It details optimal supervisory control problems arising in automated production systems and outlines a methodology to achieve the optimality purposes of deadlock prevention via converting a variety of problems under consideration into integer linear programming models. The book includes a reference bibliography at the end of each chapter and a complete index.

The book is written for an undergraduate course on the Modern Control Systems. It provides comprehensive explanation of state variable analysis of linear control systems and analysis of nonlinear control systems. Each chapter starts with the background of the topic. Then it gives the conceptual knowledge about the topic dividing it in various sections and subsections. Each chapter provides the detailed explanation of the topic, practical examples and variety of solved problems. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting. The book starts with explaining the concept of state variable and state model of linear control systems. Then it explains how to obtain the state models of various types of systems using phase variables, canonical variables, Jordan's canonical form and cascade programming. Then the book includes good coverage of the matrix algebra including eigen values, eigen vectors, modal matrix and diagonalization. It also includes the derivation of transfer function of the system from its state model. The book further explains the solution of state equations including the concept of state transition matrix. It also includes the various methods of obtaining the state transition matrix such as Laplace transform method, Power series method, Cayley Hamilton method and Similarity transformation method. It further includes the detailed discussion of controllability and observability of systems. It also provides the discussion of pole placement technique of system design. The book teaches various types of nonlinearities and the nonlinear systems. The book covers the fundamental knowledge of analysis of nonlinear systems using phase plane method, isocline method and delta method. Finally, it explains stability analysis of nonlinear systems and Liapunov's stability analysis.

The importance of electric motors is well known in the various engineering fields. The book provides comprehensive coverage of the various types of electric motors including d.c. motors, three phase and single phase induction motors, synchronous motors, universal motor, a.c. servomotor, linear induction motor and stepper motors. The book covers all the details of d.c. motors including torque equation, back e.m.f., characteristics, types of starters, speed control methods and applications. The book also covers the various testing methods of d.c. motors such as Swinburne's test, brake test, retardation test, field test and Hopkinson's test. The book further explains the three phase induction motors in detail. It includes the production of rotating magnetic field, construction, working, effect of slip, torque equation, torque ratios, torque-slip characteristics, losses, power flow, equivalent circuit, effect of harmonics on the performance, circle diagram and applications. This chapter also includes the discussion of induction generator. The book teaches the various starting methods and speed control methods of three phase induction motors. The book incorporates the explanation of various single phase induction motors. The chapter on synchronous motor provides the detailed discussion of construction, working principle, behavior on load, analysis of phasor diagram, Vee and Inverted Vee curves, hunting, synchronous condenser and applications. The book also teaches the various special machines such as single phase commutator motors, universal motor, a.c. servomotor, linear induction motor and stepper motors. The book uses plain, lucid language to explain each topic. The book provides the logical method of explaining the various complicated topics and stepwise methods to make the understanding easy. Each chapter is well supported with necessary illustrations, self explanatory diagrams and variety of solved problems. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting.

The importance of transformers and generators is well known in the various engineering fields. The book provides comprehensive coverage of the various types of transformers, d.c. generators and synchronous generators (alternators). The book starts with the brief review of single phase transformer. It continues to discuss no load and on load performance of transformers, phasor diagrams, equivalent circuit, voltage regulation and all day efficiency of transformer. The detailed discussion of open and short circuit tests and predetermination of regulation and efficiency is also included in the book. The chapter on three phase transformer provides the detailed discussion of construction, three phase transformer connections and phasor groups. The book also explains parallel operation of transformers, tap changing transformer, autotransformers, cooling of transformers and three winding transformer. The various testing methods of transformers are also incorporated in the book. The book covers all the details of d.c. generators including construction, armature reaction, commutation, characteristics and applications. The chapters on synchronous generators starts with the explanation of basics of synchronous generators including construction, winding details, e.m.f. equation and effect of harmonics on induced e.m.f. The book then explains the concept of armature reaction, phasor diagrams, regulation and various methods of finding the regulation of alternator. Stepwise explanation and simple techniques used to elaborate these methods is the feature of this book. The book further explains the concept of synchronization of alternators, two reaction theory and parallel operation of alternators. The book uses plain, lucid language to explain each topic. The book provides the logical method of explaining the various complicated topics and stepwise methods to make the understanding easy. Each chapter is well supported with necessary illustrations, self explanatory diagrams and variety of solved problems. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting.

This book presents topics in an easy to understand manner with thorough explanations and detailed illustrations, to enable students to understand the basic underlying concepts. The fundamental concepts, graphs, design and analysis of control systems are presented in an elaborative manner. Throughout the book, carefully chosen examples are given so that the reader will have a clear understanding of the concepts.

The knowledge of switchgear and apparatus protection plays an important role in the power system. The book is structured to cover the key aspects of the course Switchgear & Protection for undergraduate students. The book starts with the discussion of basics of protective relaying. The book includes comprehensive coverage of faults and analysis of symmetrical and unsymmetrical faults. The book explains the protection against overvoltage, lightning arresters and power

system earthing. The book covers the characteristics of various types of relays such as electromagnetic relays, induction type relays, directional relays, differential relays, thermal relays, frequency relays and negative sequence relays. The detailed discussion of distance relays and static relays is also included in the book. The book also covers the various possible faults and methods of protection of transformers, generators, motors, busbars and transmission lines. The book further explains the theory of circuit interruption and various arc interruption methods. Finally, the book incorporates various types of circuit breakers, circuit breaker ratings and testing of circuit breakers. The book uses plain and lucid language to explain each topic. The book provides the logical method of explaining the various complicated topics and stepwise methods to make the understanding easy. Each chapter is well supported with necessary illustrations and self-explanatory diagrams. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting.

Advanced Control Engineering provides a complete course in control engineering for undergraduates of all technical disciplines. Included are real-life case studies, numerous problems, and accompanying MatLab programs.

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